



# MX14

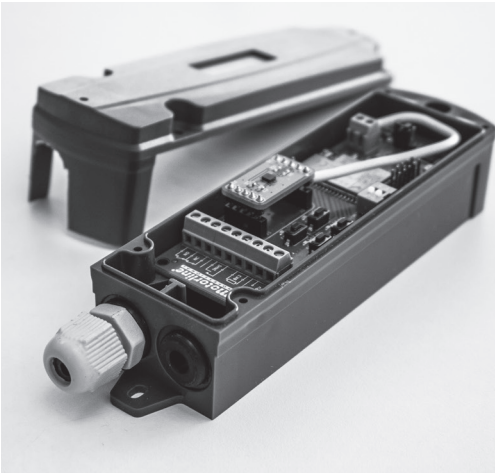


v3.3 REV. 03/2024



## OPERATION/PROGRAMMING MANUAL

EN



The MX14 is an emitter that communicates wirelessly with the MR14 receiver, up to 50m in the open, powered by batteries or rechargeable batteries by solar panel. Allows the connection of an 8k2 safety edge, optical sensor and dry contact safety device, or the use of an accelerometer.

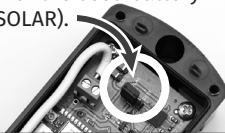
### TECHNICAL CHARACTERISTICS

• Power supply	3.6V AA batteries or 3.7V AA rechargeable batteries
• Solar panel	4V 150mA monocrystalline
• Working frequency	868.0MHz to 869.8MHz
• Reach in open field	50m
• Dimension	150 x 42 x 40 (mm)
• Protection degree	IP65



### ENERGY

Place the jumper in the position indicated for the used battery (BATT or SOLAR).



**BATTERY DURATION:**  
3 years in ECO mode;  
In NORMAL mode the use of a solar panel is recommended.



#### Battery Mode (BATT)

Lithium batteries with a power of 3.6V and size AA.



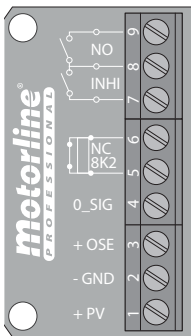
#### Solar Mode (SOLAR)

Rechargeable lithium ion batteries, powered by the solar panel, with a power of 3.7V with size AA.

**ATTENTION:** ALWAYS CHECK THE CORRECT ORIENTATION WHEN APPLYING THE BATTERY TO THE DEVICE.



### INPUTS / OUTPUTS



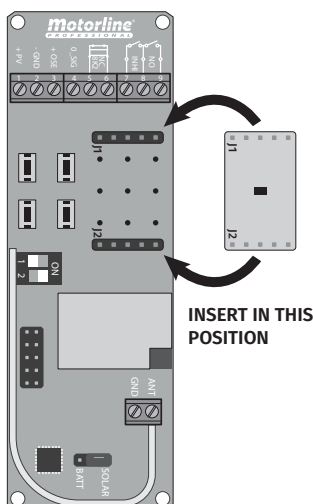
9 • NO	Input for dry contact safety devices
8 • COM	Common
7 • INHI	NO input for inhibit signal
6 • 8K2/NC	Input for 8k2 resistive safety rubber. <b>NOTE</b> • To use 8k2 Dipper 1 and 2 must be OFF. To use NC, Dipper 1 must be ON and Dipper 2 must be OFF.
5 • 8K2	
4 • 0_SIG	Optical sensor signal
3 • + OSE	Optical sensor power supply
2 • GND	Solar panel and optical sensor common
1 • + PV	



It is possible to invert the polarity of the auto test channel inputs through the MR14 pin headers.



### ACCELEROMETER - Inclination Sensor



The accelerometer is not included in the kit.

The accelerometer (tilt sensor) allows you to measure the level of tilt and speed of your vibrations, allowing you to detect obstacles during door or gate maneuvers.



To use this sensor, you must put Dipper2 to ON.

#### AUTOMATIC SENSOR PROGRAMMING:

- 1 • Press the PROG button for 5 seconds to enter the programming mode.
- 2 • Carry out opening and closing maneuvers.
- 3 • After closing, you can change the FORCE and/or TILT values by pressing the respective button as many times as necessary until reaching the desired value (the level is identified by the number of times the respective LED flashes).
- 4 • Press the PROG button again to exit the programming mode.

#### CHANGE THE SENSOR'S FORCE AND TILT VALUES:

- 1 • Press the PROG button once.
- 2 • Pressing the FORCE and/or TILT button as many times as necessary until reaching the desired value (the level is identified by the number of times the respective LED flashes)
- 3 • Press the PROG button again to exit programming mode.



## RECHARGEABLE BATTERIES



Rechargeable batteries may be dead if they are not used for some time. In this case, the first time they are used, it is necessary to wait for the solar panel to recharge them.



## DIPPER

	DIPPER 1	DIPPER 2
• 8K2	OFF	OFF
• NC	ON	OFF
• Accelerometer	OFF	ON
• Optical sensor	ON	ON

The dippers allow you to select the operation of the MX14 with 8K2, NC, NO, OSE sensor or tilt sensor.

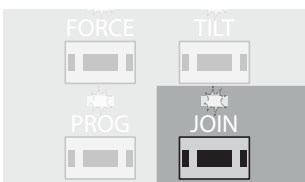


## BUTTONS AND LEDS



Each MX14 can only be programmed into a one MR14

### JOIN → SEND SIGN



#### • BUTTON

> To erase or store on an MR14, press the button for 1.5 seconds.

#### • LED

> Flashes 5 times when stored on an MR14.

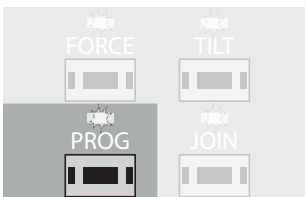
> Flashes 1 time when erased on an MR14

**NOTE** • Even if it is programmed on an MR14, the LED will remain off to save energy.

> When you start the device, the LED flashes once to indicate that it has power. If it is stored in an MR14, the PROG LED will also flash.

### PROG → AUTOMATIC PROGRAMMING OF FORCE AND TILT VALUES FOR ACCELEROMETER

**OPERATION:** This menu is used to automatically record the maximum values FORCE and TILT during the movement of the gate.



#### • BUTTON

> Press button for 1,5 seconds to enter Programming Mode.

> When programming is complete, press once to confirm and exit this mode.

**NOTE** • If you press and release immediately, you will enter the programming mode to change only the FORCE and TILT values, keeping the programming of the door.

**WARNING** • You can only enter Programming Mode if Dipper2 is ON (Accelerometer mode)

#### • LED

ON - Programming mode active

OFF - Inactive programming mode

### FORCE → DEFINITION OF FORCE / MAXIMUM SENSOR TILT SPEED (8 LEVELS)

**OPERATION:** Whenever the force / speed of the incline is greater than the defined level, the device will send a signal to the MR14.

#### • BUTTON

> Press PROG once

> Press FORCE the necessary times until you reach the desired level

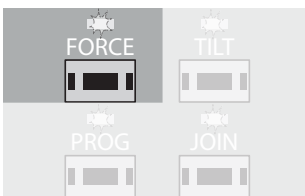
> Press PROG once to exit programming mode

**WARNING** • You can only enter Programming Mode if Dipper2 is ON (Accelerometer mode)

#### • LED

> Each LED flash represents 1 power level.

**Example:** FORCE LED flashes 4 times, indicates the force/speed level is 4.



### TILT → SENSOR MAXIMUM ANGLE DEFINITION (8 LEVELS)

**OPERATION:** Whenever the degree of inclination is higher than the defined level, the device will send signal to the MR14.

Each level is approximately one degree (1st) of inclination.

#### • BUTTON

> Press PROG once

> Press FORCE as often as necessary until you reach the desired level

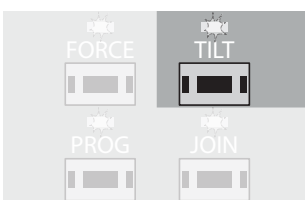
> Press PROG once to exit programming mode

**WARNING** • You can only enter Programming Mode if Dipper2 is ON (Accelerometer mode)

#### • LED

> Each LED flashing represents 1 level of the tilt angle.

**Example:** TILT LED flashes 4 times, indicating that the tilt level is 4.



### CHANGE FREQUENCY:

You must use the same frequency on the MX14 that is programmed on the MR14 receiver. Whenever there are other MX14 and MR14 connected to each other nearby, you must use other frequencies to prevent interference.

- 1 • Press the PROG and JOIN buttons at the same time until the JOIN led starts flashing.
- 2 • Press the JOIN button as many times as necessary until you reach the desired frequency.
- 3 • Press the PROG and JOIN buttons at the same time to save and exit.

The JOIN led indicates the selected frequency.

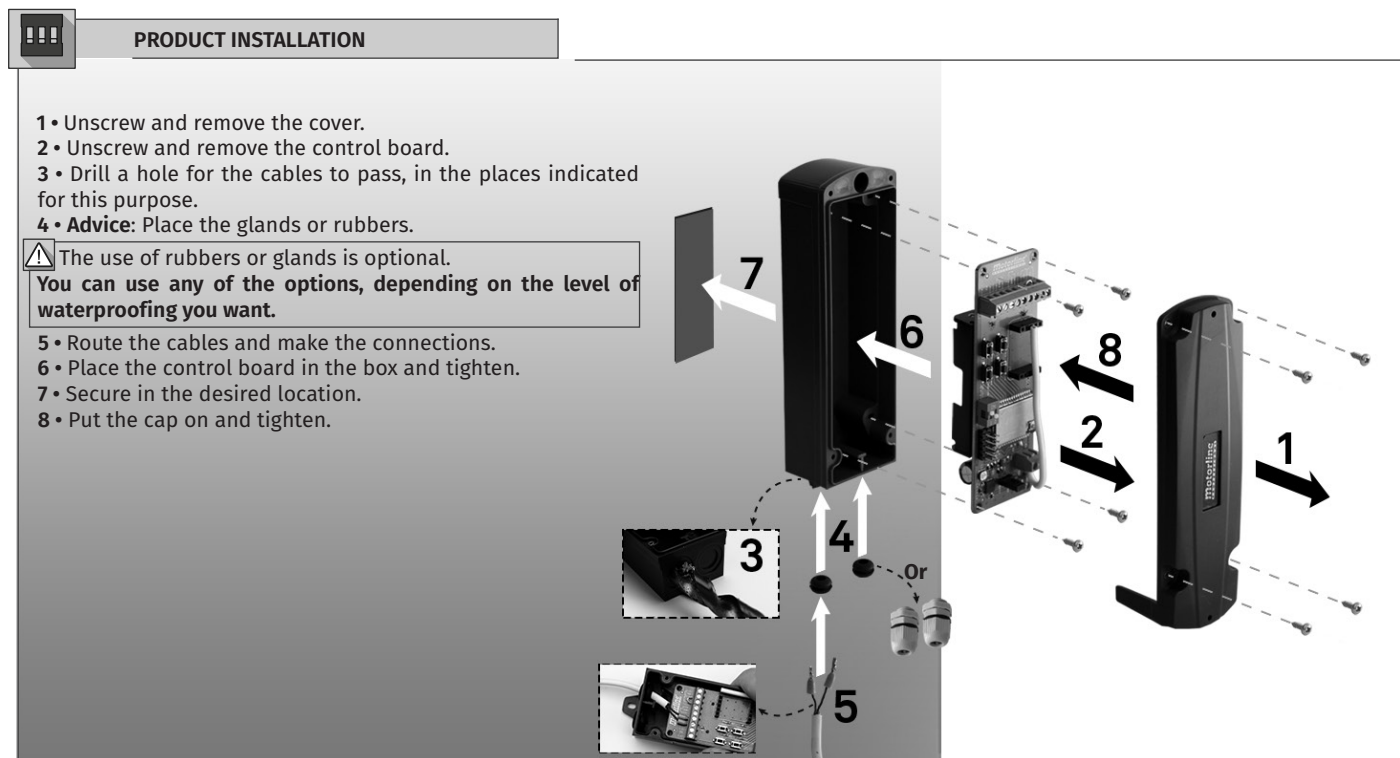
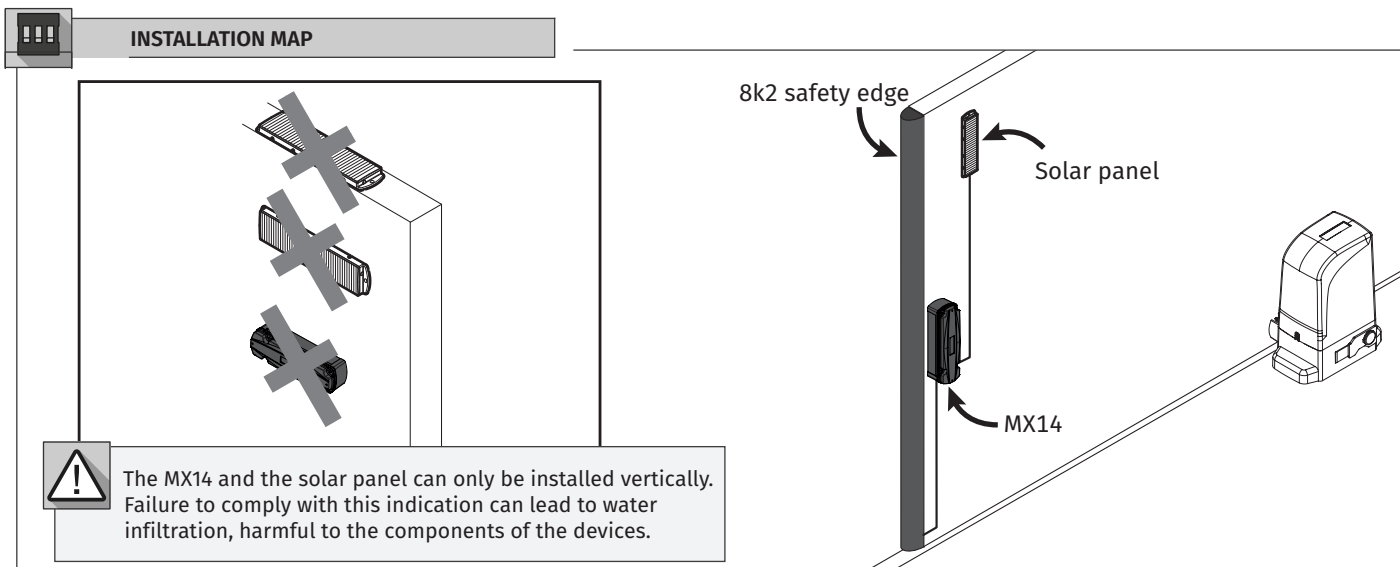
FLASHING	1	2	3	4
FREQUENCY	868 MHz	868.6 MHz	869.2 MHz	869.8 MHz

### DELETE EMITTER:

- 1 • Press the emitter's JOIN button until the transmitter's JOIN LED flashes once.

#### NOTE • To delete when there is no communication between devices (MR14):

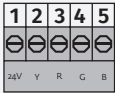
- 1 • Press PROG button to select the position you want to delete.
- 2 • Press the JOIN button to open the selected position (the position LED will flash quickly).
- 3 • Press the JOIN button again to delete the emitter from that position.
- 4 • The position LED stops flashing and goes off, signaling the success of the operation.



## CONNECTION SCHEME



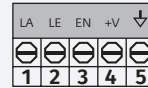
Check the manual for your control board to identify the entries corresponding to the one indicated in the diagram.



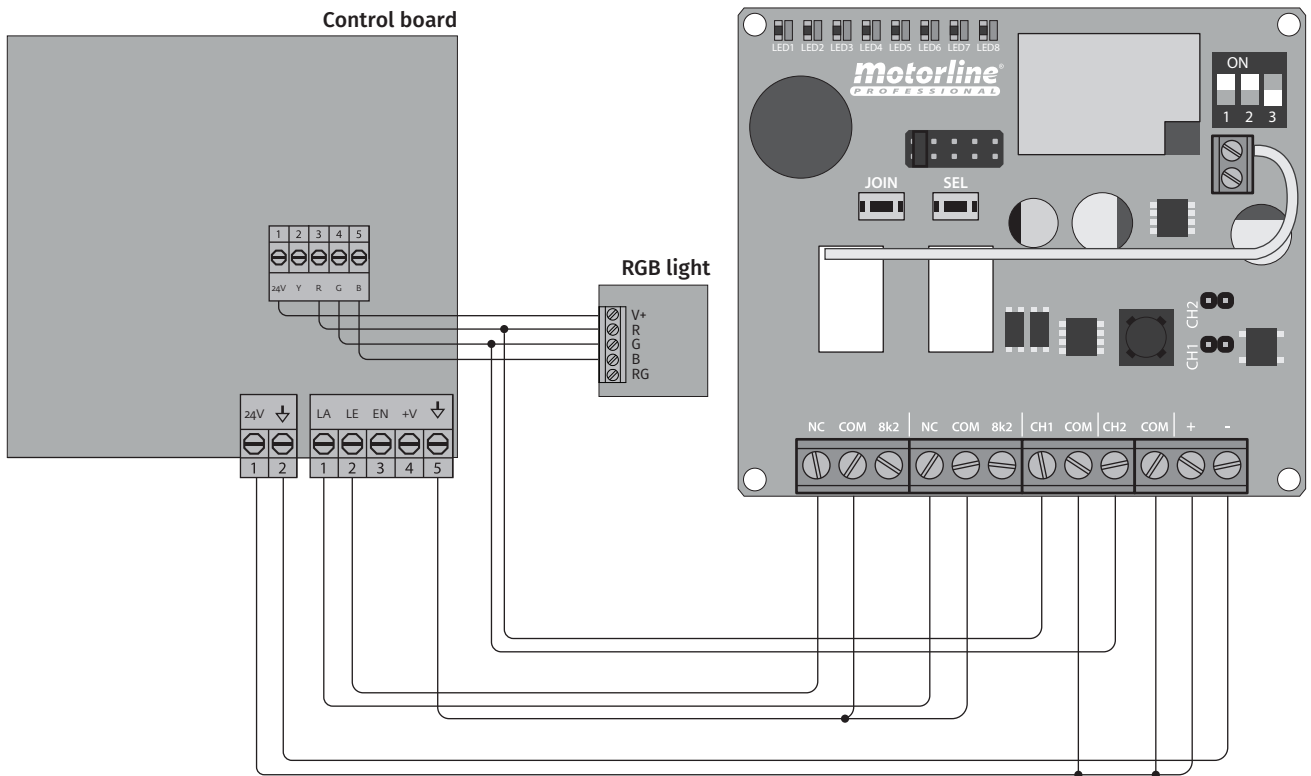
- 1 • 24V → 24V output
- 2 • (not used)
- 3 • R → 0V output - activated during closing maneuvers
- 4 • G → 0V output - activated during opening maneuvers
- 5 • B → 0V output - activated during pause time



- 1 • 24V output (minimum → 100mA)
- 2 • COM



- 1 • LA → Safety edge input
- 2 • LE → Photocells input
- 3 • (not used)
- 4 • (not used)
- 5 • COM



Dry contact safety devices NO

Signal inhibitor

• When closed (NC), the emitter will ignore signals from inputs 8k2 NO/NC and optical sensor.

Optical sensor

Solar panel

8k2 or NC resistive safety rubber

• To use, remove the resistance that comes from the factory at inputs 5 and 6.

MX14

